

The Design, Validation, and Applications of Observing System Simulation Experiments

By

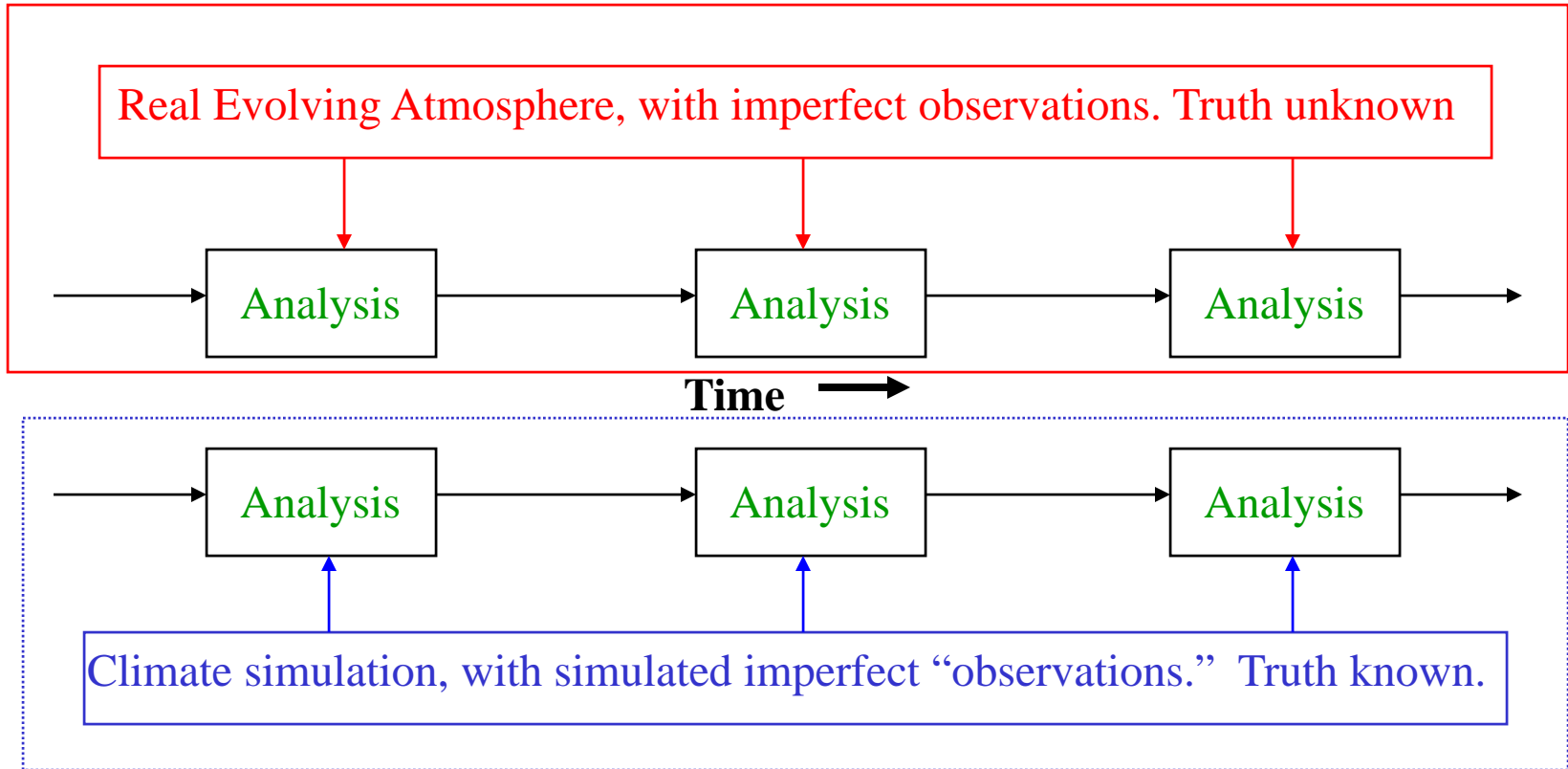
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Outline

1. OSSE basics
2. The OSSE project at GMAO
3. Validation metrics
4. Use of an OSSE to evaluate a DAS
5. Warnings

Data Assimilation of Real Data



Observing System Simulation Experiment

Applications of OSSEs

1. Be able to estimate the effect of proposed instruments on analysis and forecast skill by “flying” them in a simulated environment.
2. Be able to evaluate present and proposed data assimilation techniques in a simulation where “truth” is known perfectly.

Requirements for an OSSE system

1. A self-consistent and realistic simulation of nature.
2. Simulation of all presently-utilized observations, derived from the “nature run” and having simulated instrument plus representativeness errors characteristic of real observations.
3. A validated baseline assimilation of the simulated data that, for various relevant statistics, produces values similar to corresponding ones in a real DAS.

Choice of a Nature Run

1. A good simulation of nature in all important aspects
2. Ideally, individual realizations of the NR should be indistinguishable from corresponding realizations of nature (e.g., analyses) at the same time of year.
3. Since a state-of-the-art OSSE will require a cycling DAS, the NR should have temporal consistency.
4. For either 4DVAR or FGAT 3DVAR, NR datasets should have high frequency (i.e., < 6 hours)
5. Since dynamic balance is an important aspect of the atmosphere affecting a DAS, the NR datasets should have realistic balances.
6. For these and other reasons, using a state-of-the-art NWP model having a demonstrated good climatology to produce NR data sets is arguably the best choice.

Results using a Kalman Filter

Applied to a linear model with white noise error, etc.

Analysis

$$\mathbf{x}_a = \mathbf{x}_b + \mathbf{B}\mathbf{H}^T [\mathbf{R} + \mathbf{H}\mathbf{B}\mathbf{H}^T]^{-1} [\mathbf{y} - \mathbf{H}\mathbf{x}_b]$$

Analysis error covariance

$$\mathbf{A} = (\mathbf{B}^{-1} + \mathbf{H}^T \mathbf{R}^{-1} \mathbf{H})^{-1}$$

Forecast Error

$$\mathbf{B} = \mathbf{M}\mathbf{A}^{(n-1)}\mathbf{M}^T + \mathbf{Q}$$

\mathbf{R} includes instrument plus representativeness error

$$\mathbf{R} = \mathbf{E} + \mathbf{F}$$

Therefore $\mathbf{A} = \mathbf{A}(\mathbf{E}, \mathbf{F}, \mathbf{Q}, \mathbf{M})$

Daley and Menard 1993 MWR

Characteristics of Real Errors

1. Generally unknown
2. Even statistics not well known
3. Often biased
4. Correlated (maybe even with background error)
5. Include gross errors
6. Generally non-Gaussian
(a result of 5 or some basic physics; e.g. nonlinearity)

The GMAO OSSE Project

NASA Personnel: Ronald Errico, Runhua Yang, Will McCarty, Meta Sienkiewicz, Emily Liu, Ricardo Todling, Ronald Gelaro, Jing Guo, Arlindo da Silva, Ravi Govindaraju Michele Reinecker, Joanna Joiner (200+ years of expertise, mostly in data assimilation)

Consultations with JCSDA, NCEP, NESDIS, ECMWF

Some support from NSF

Immediate Goal

Quickly generate a prototype baseline set of simulated observations that is significantly “more realistic” than the set of baseline observations used for the previous NCEP/ECMWF OSSE.

Account for:

Resources are somewhat limited

The Nature Run may be unrealistic in some important ways

Some issues are not very important compared to others

Some important issues may still have many unknown aspects

Two Ways of Generating Observations

1. Create observations as realistically as possible

Most complete way of incorporating realism

Less prone to erroneous pre-judgements about importance

Many obs not used due to data thinning

Must incorporate gross errors (need statistics model)

Some obs characteristics may be irrelevant (e.g., cloudy IR)

May need to adjust due to NR deficiencies (e.g., precip)

2. Create observations with realistic distributions and error statistics

Minimal but necessary requirement for simulating observations

Must decide and consider what is important

Can ignore some aspects of obs (e.g., many details of gross errors)

Can ignore details of some portions of DAS algorithm (e.g, QC)

Can design with flexibility to account for NR unrealism

The OSSE problem: DAS : $\mathbf{x}_a - \mathbf{x}_b = \mathbf{K} [\mathbf{y} - H(\mathbf{x}_b)]$
OSSE obs: $\mathbf{y} = H'(\mathbf{x}_{NR})$

1. The information provided to the DAS by the observations are the *innovations* $\mathbf{y} - H(\mathbf{x}_b)$.
2. Differences between the operators H and H' contribute to the innovations in a way that is interpreted by the DAS as a contribution to the *representativeness* error.
3. Making H' more realistic but concurrently more unlike H acts to make the representativeness error more realistic rather than to increase the observation information content unusable by the DAS.
4. A valid OSSE requires that the characteristics of rep. + instrument errors, including their non-Gaussian aspects, are sufficiently considered and adequately simulated.

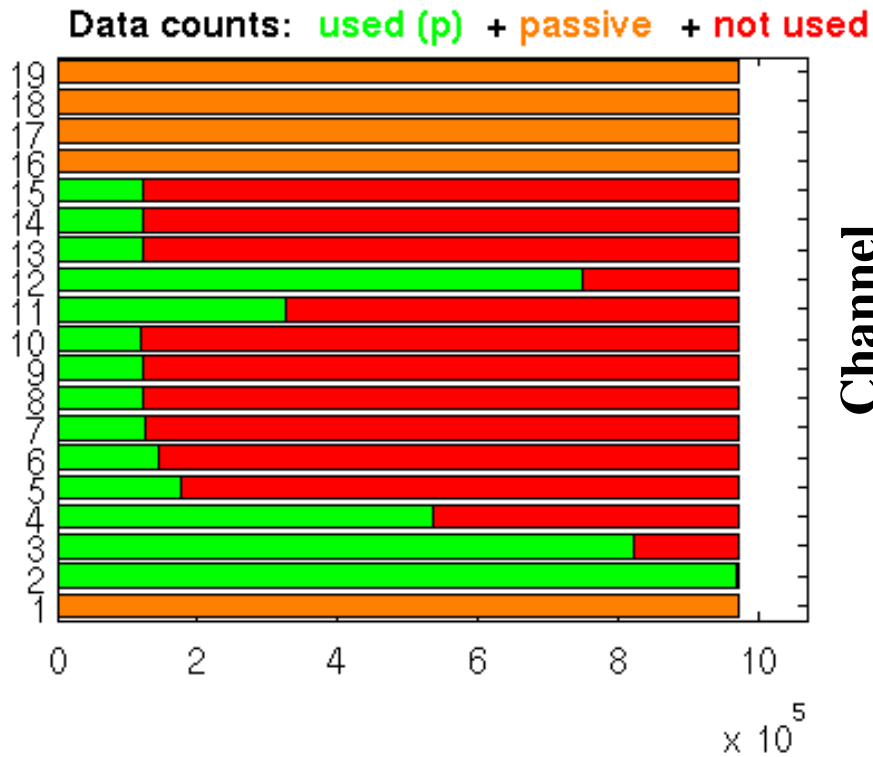
Validation Metrics

1. Data assimilation is a fundamentally statistical problem, and an observing system therefore can only be reliably evaluated statistically.
2. For a NR given by a free-running NWP model solution, there is no correspondence between realizations of “weather” in it and in the real world on any specific date.

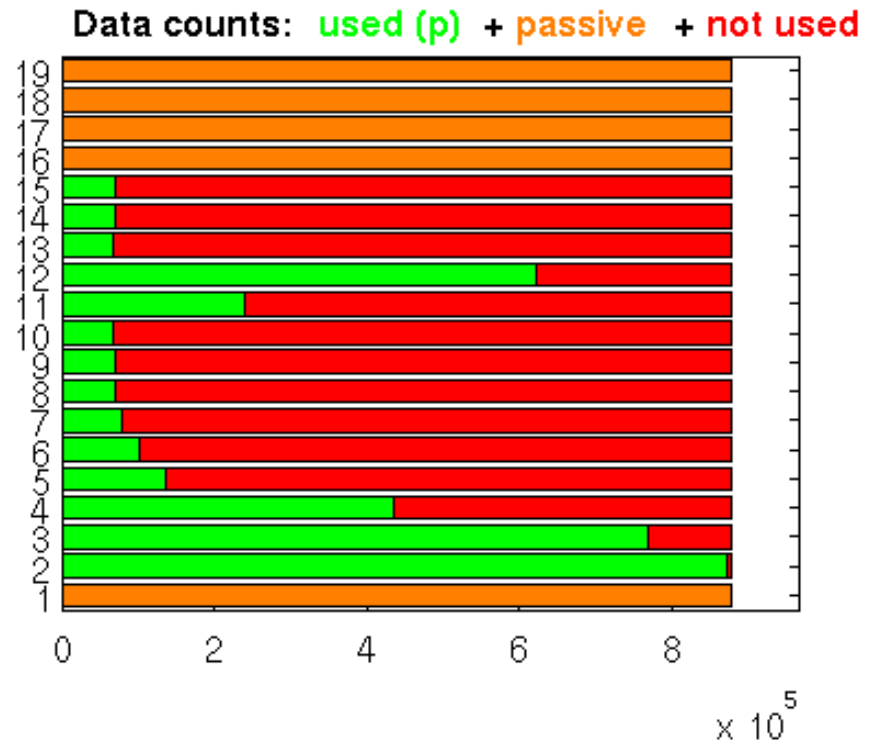
Validation of numbers of assimilated obs

Example from GMAO OSSE test for HIRS-3, NOAA-17, Jan 2006

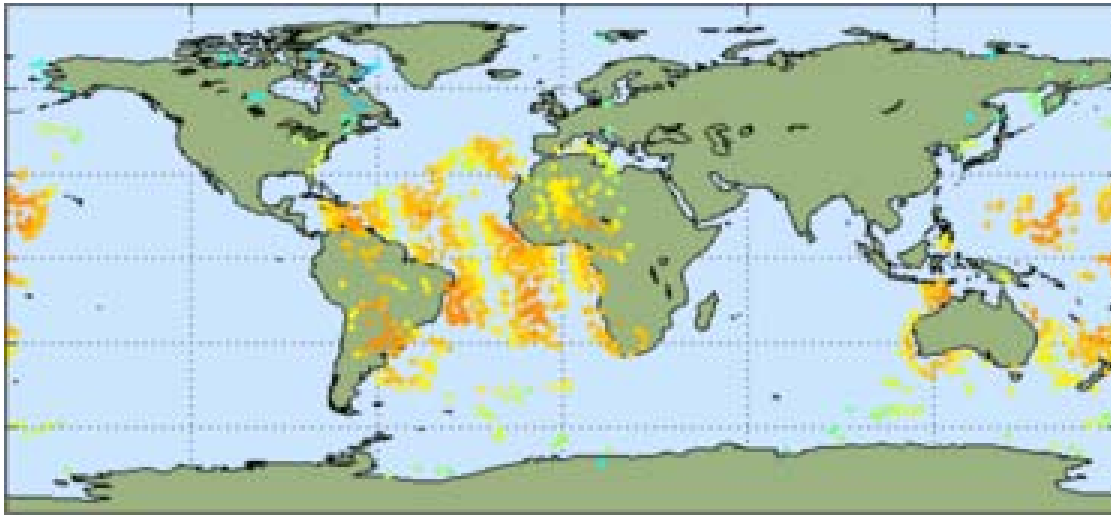
OSSE DAS



Reference DAS



Validation of spatial distribution of assimilated obs

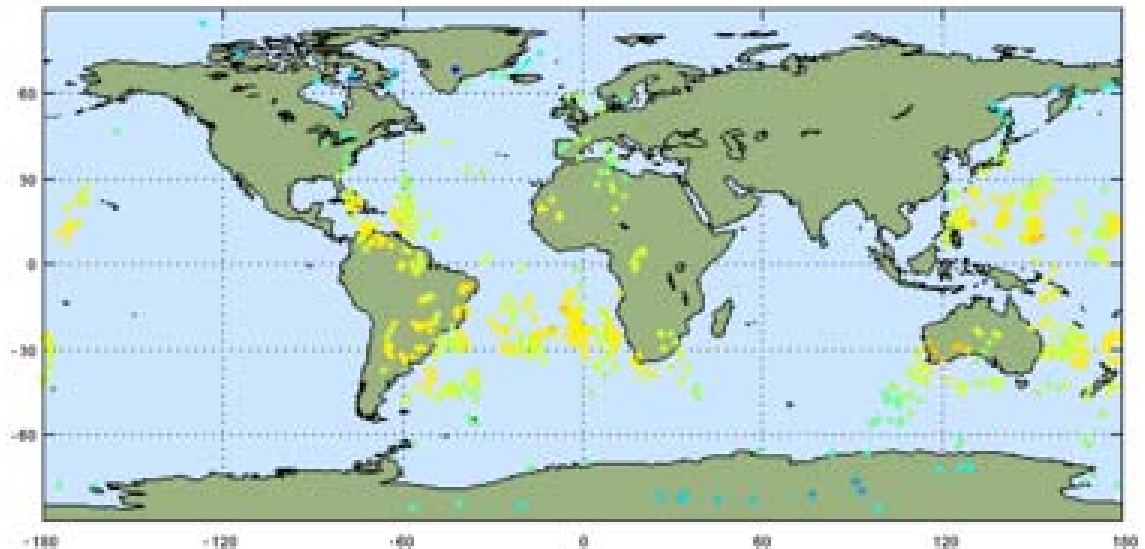


OSSE Data

Locations of Brightness
Temperature accepted by
the Quality-Control for
NOAA-17 channel 7
HIRS-3 on 15 Jan 2006
at 0 UTC +/- 3hrs

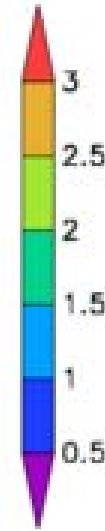
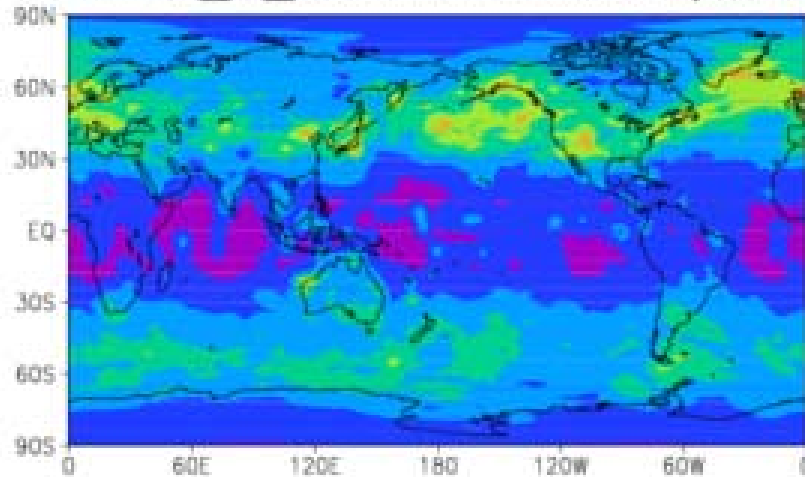
Ignore colors

Real Data



Validation of analysis increment ($x_a - x_b$) statistics

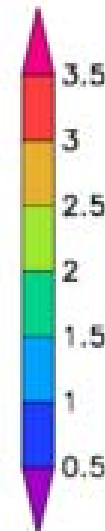
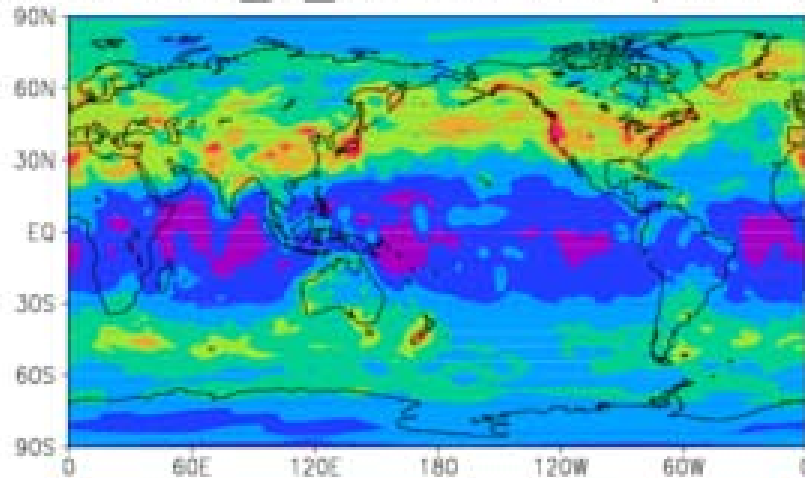
stdv of Ainc_U_500mb v4osse (Jan. 2006)



OSSE

Standard deviations
of analysis increments
u field, 500 mb

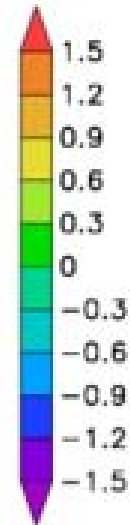
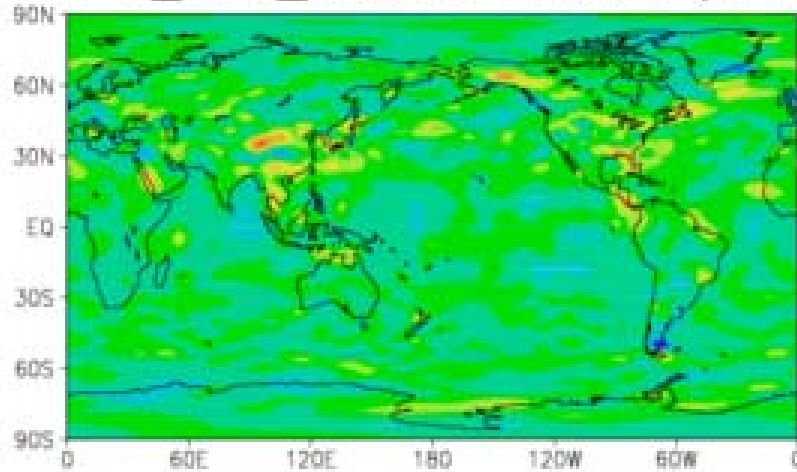
stdv of Ainc_U_500mb CTL (Jan. 2006)



Real

Validation of analysis increment ($x_a - x_b$) statistics

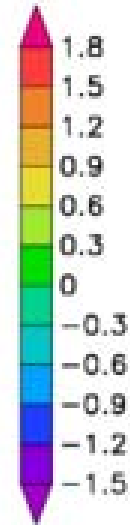
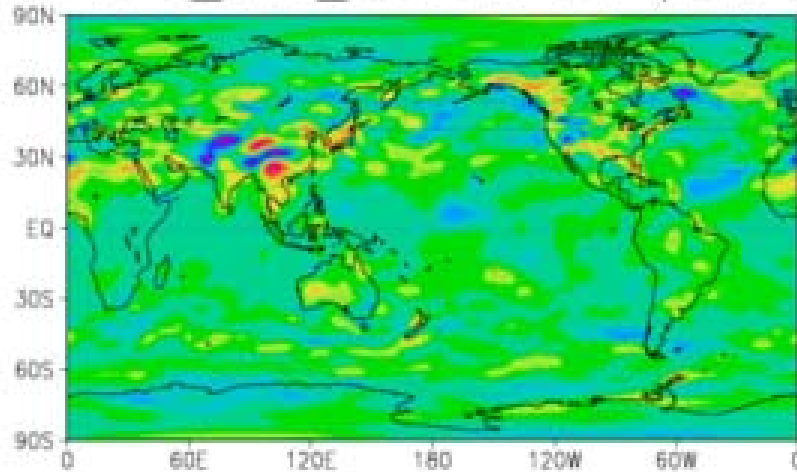
mean of U_Ainc_500mb v4osse (Jan. 2006)



OSSE

mean values
of analysis increments
u field, 500 mb

mean of U_Ainc_500mb CTL (Jan. 2006)

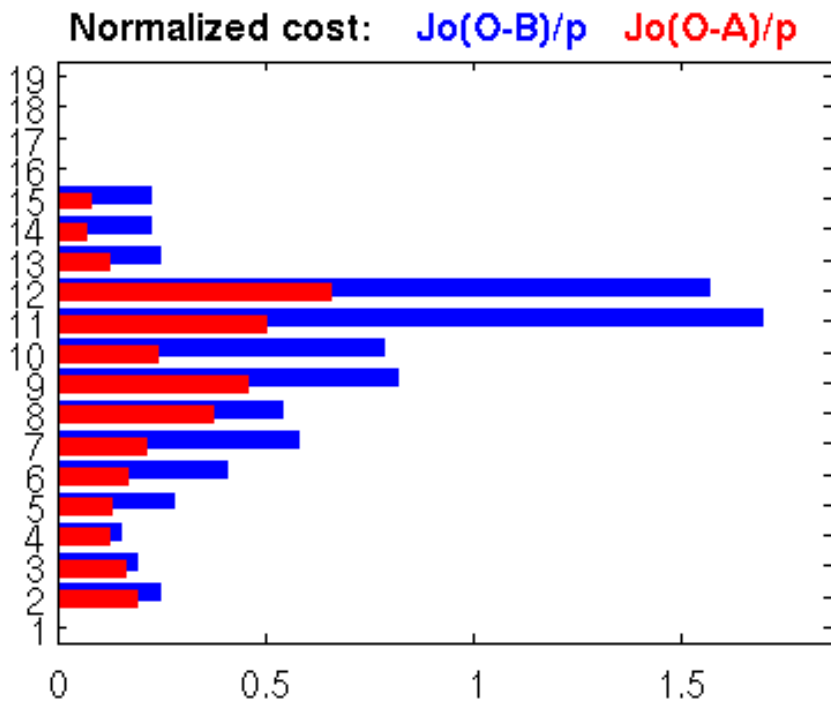


Real

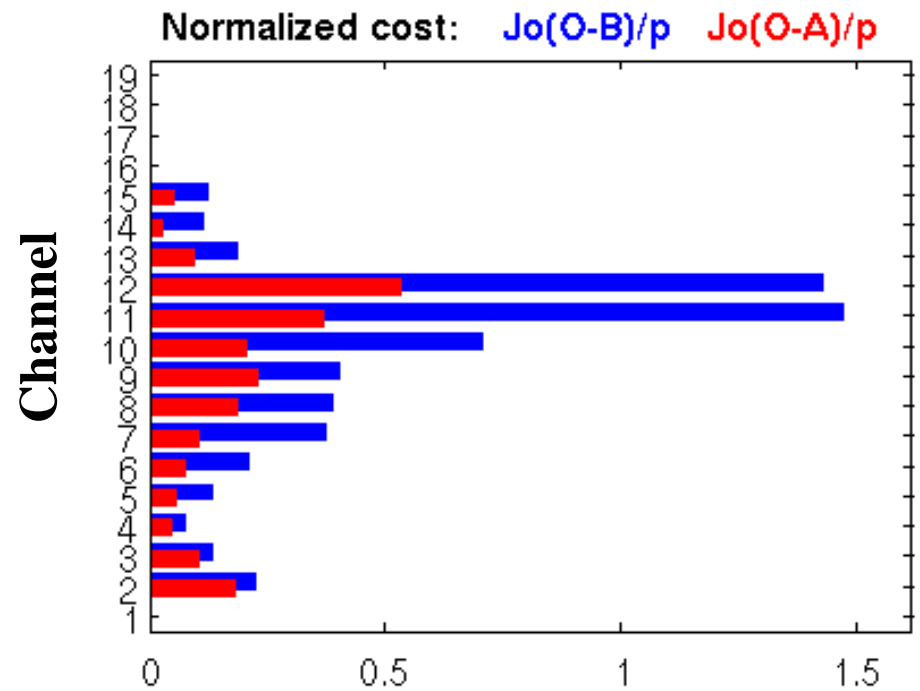
Validation of O-F and O-A statistics

Example from GMAO OSSE test for HIRS-3, NOAA-17, Jan 2006

OSSE DAS

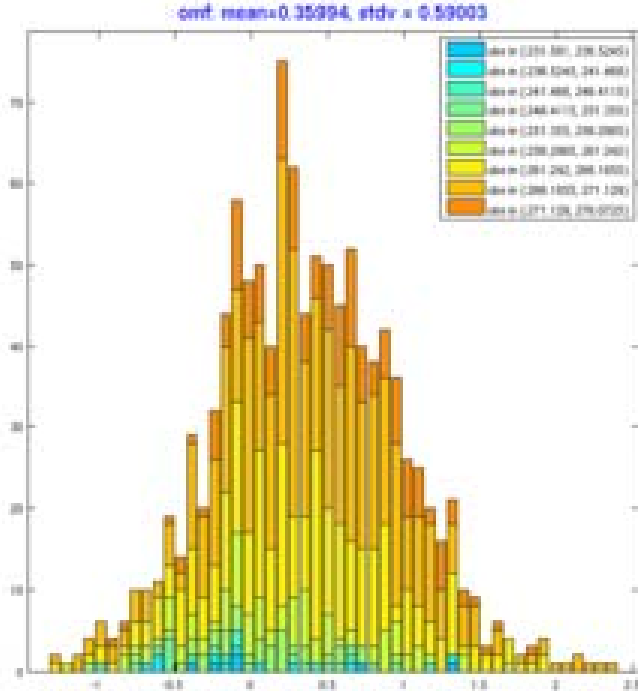


Reference DAS

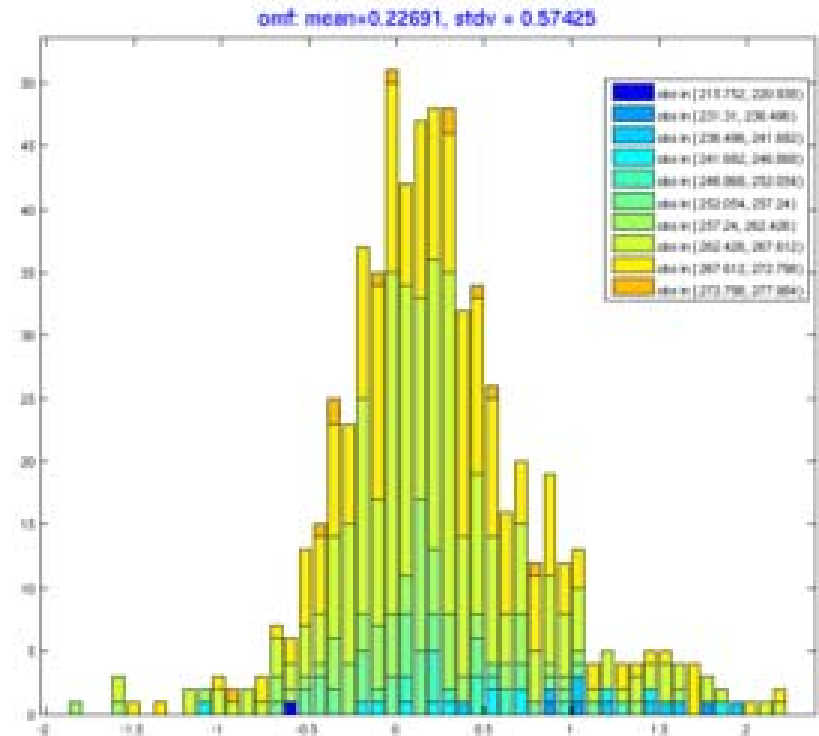


Validation of O-F distribution

Distribution of Innovations (O-F) of Brightness Temperature accepted by the Quality-Control for NOAA-17 channel 7 HIRS-3 on 15 Jan 2006 at 0 UTC +/- 3hrs Ignore colors



OSSE Data

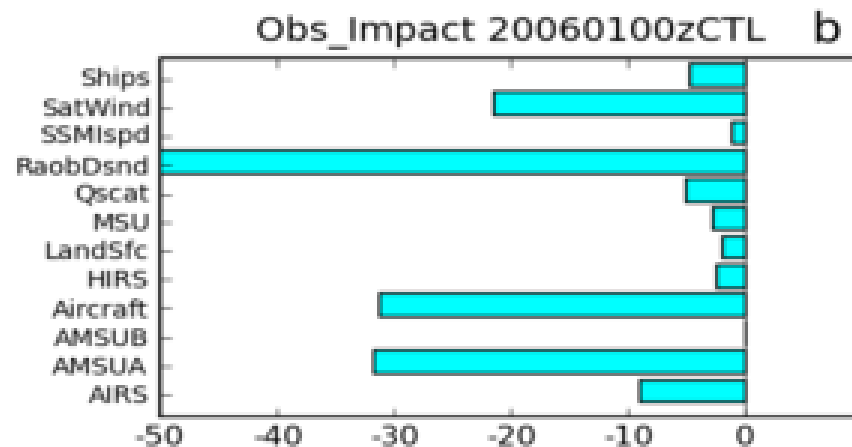
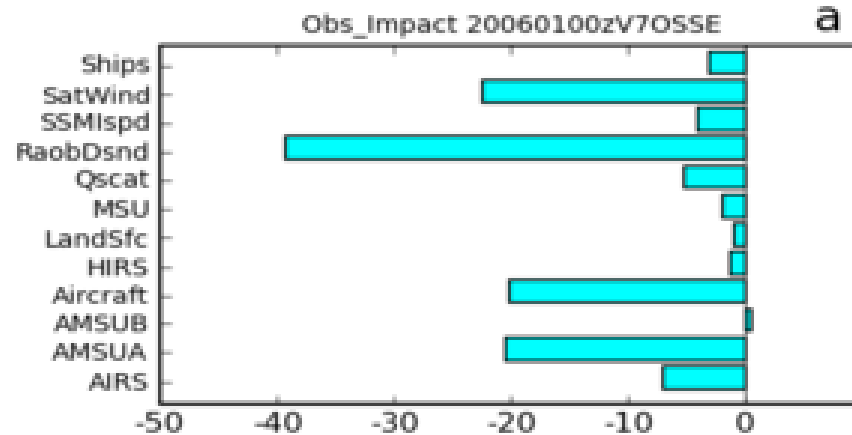


Real Data

Validation of Obs Impacts

Adjoint-derived estimates of observation impacts

$J=2*KE+APE$ of 24-hour forecast error



Validation of Forecast Skill

Use of an OSSE to evaluate a DAS

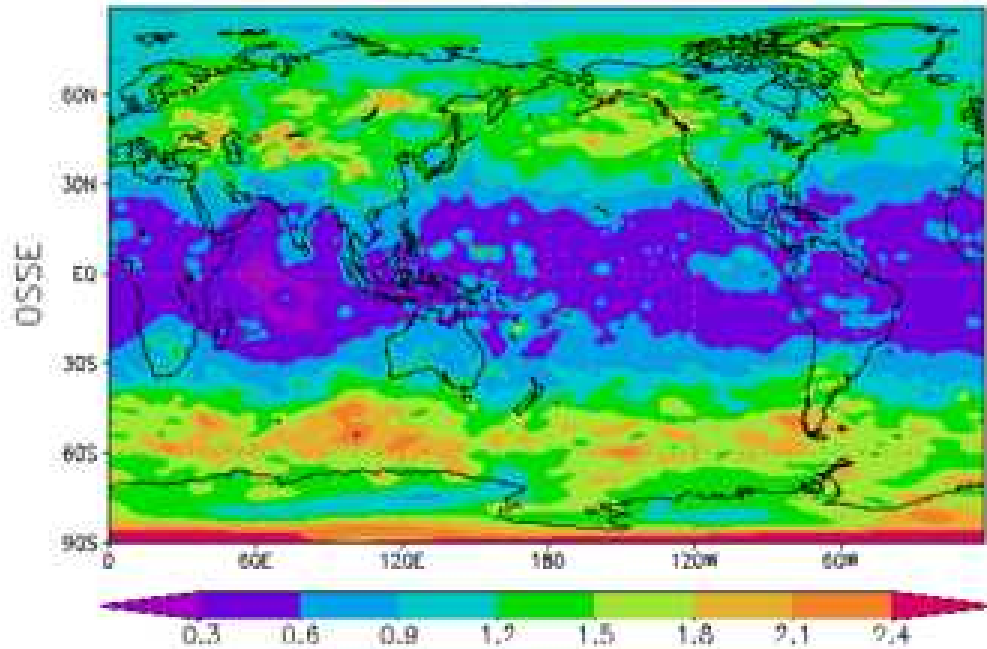
Errico, R.M., R. Yang, M. Masutani, M., and J. Woollen, 2007: Estimation of some characteristics of analysis error inferred from an observation system simulation experiment. *Meteorologische Zeitschrift*, **16**, 695-708.

Nature Run: ECMWF 1993 model T213L31, 5-week simulation

DAS: NCEP SSI system from 2005 at T170L42 resolution

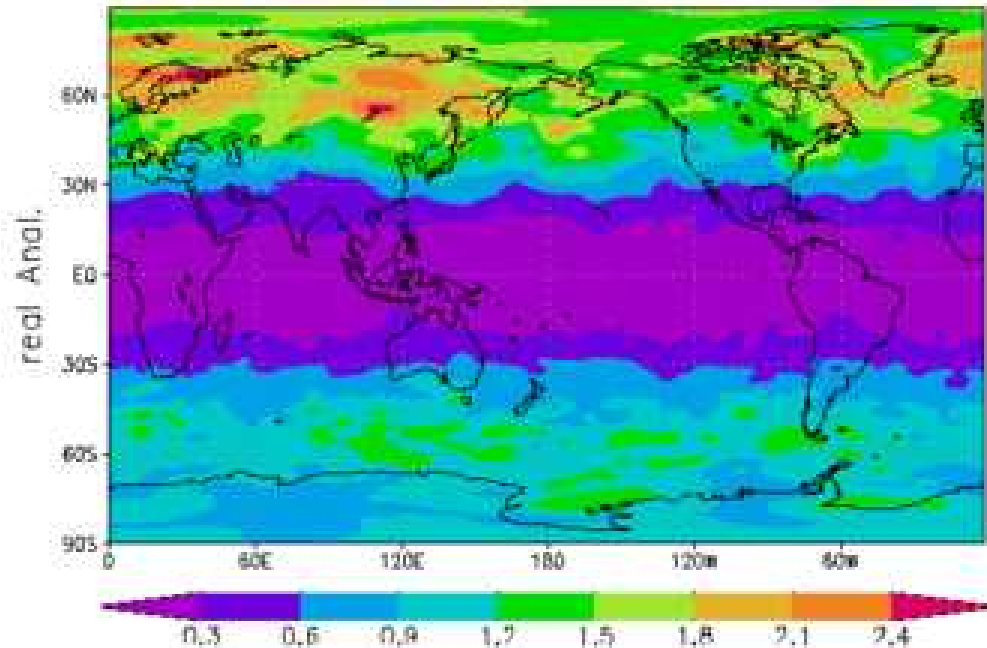
Standard Deviation of the
analysis increment for the
u-wind in the former
NCEP/ECMWF OSSE

stdv Ainc_U at 494mb

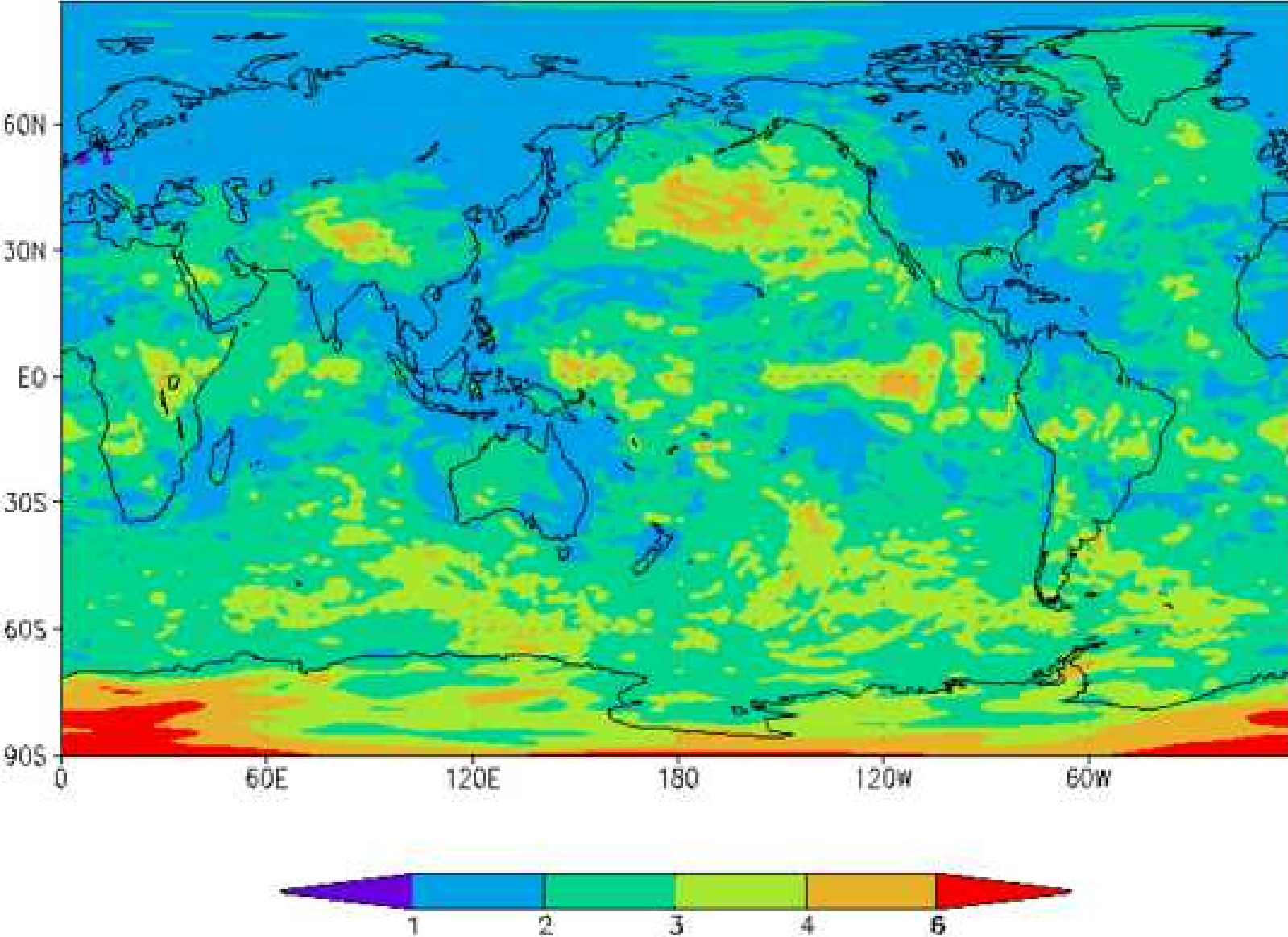


T170L42 resolution
Feb. 1993 obs network

stdv Ainc_U at 494mb

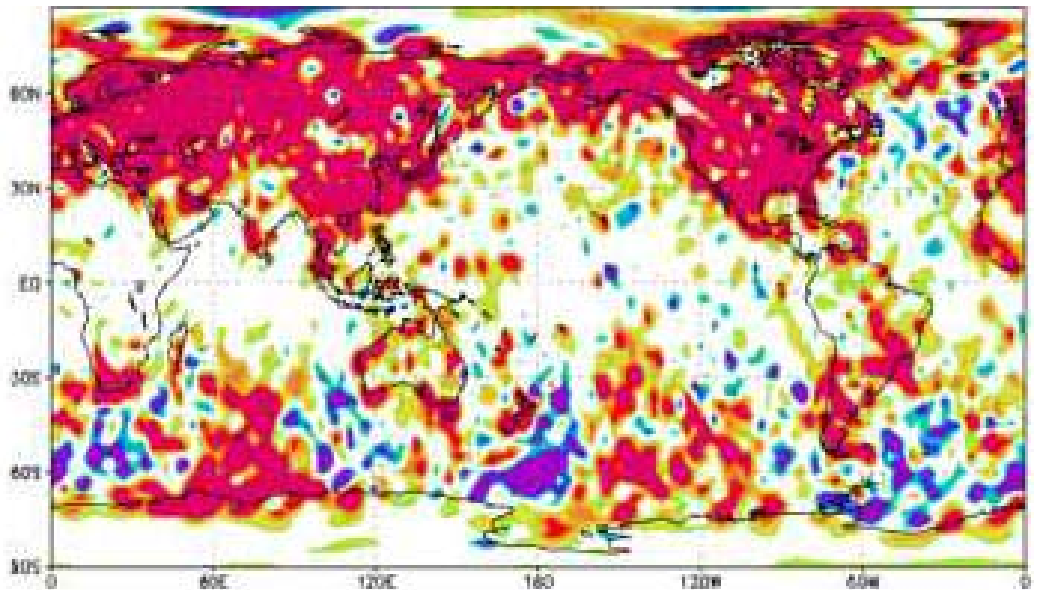
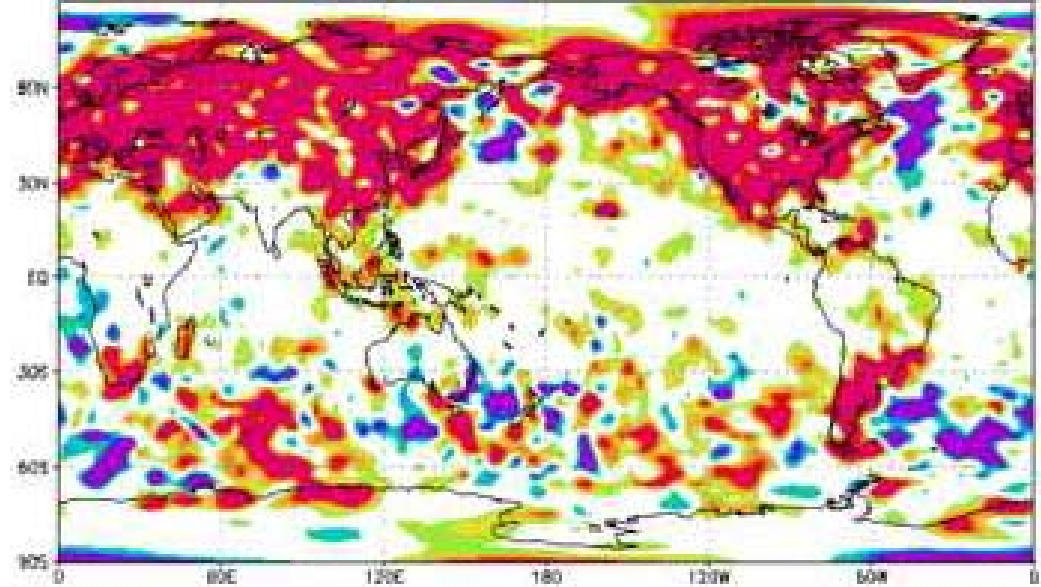


Analysis error standard deviations: u on eta=0.5 surface



Measured
Gain at 12Z
~500 mb

$$\text{gain} = \frac{\sigma_b^2 - \sigma_a^2}{\sigma_b^2}$$

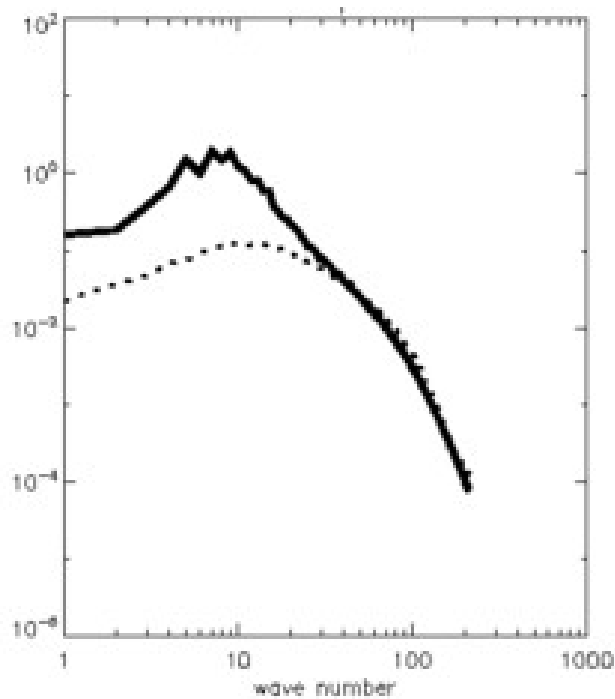


Horizontal 2-D Spectra of Transient Fields at ~716 mb 12Z, T170

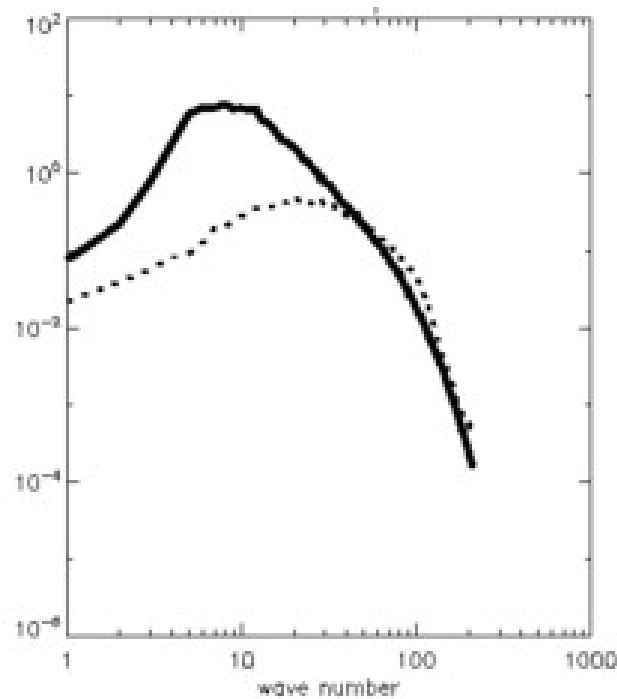
Solid=Nature Run

Dotted = Analysis Error

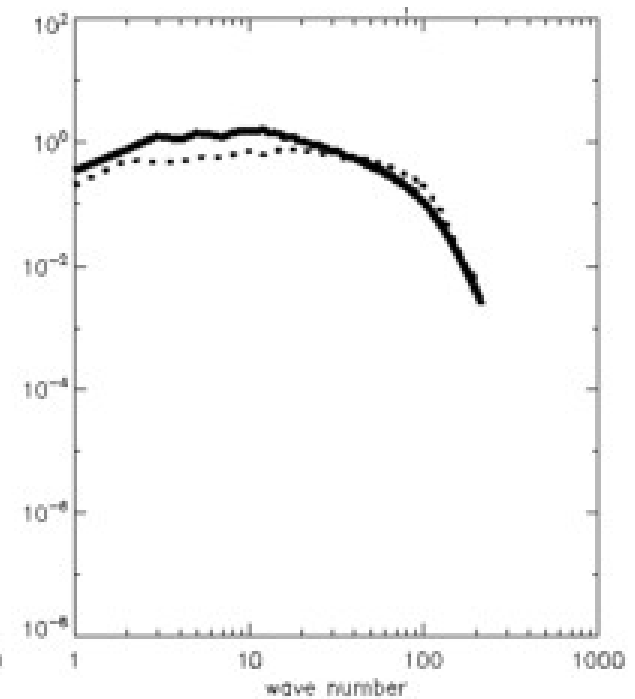
Temperature



Rotational KE



Divergent KE X 10



Warnings

Past problems with some OSSEs

1. Some OSSEs use “no obs” as control
2. Some OSSEs have no validation of their control DAS
3. Some OSSEs are based on very limited “case studies”
4. Some OSSEs use unrealistic obs errors (e.g., no rep. error)
5. Some OSSEs use a very deficient NR

Warnings

General criticisms of OSSEs

1. In OSSEs, the NR and DAS models are generally too alike, therefore underestimating model error and yielding overly-optimistic results.
2. When future specific components of the observing systems are deployed, the system in general will be different as will the DAS techniques, and therefore the specific OSSE results will not apply.
3. OSSEs are just bad science!

Response to Warnings

1. Design OSSEs more thoughtfully.
2. Validate OSSEs more carefully.
3. Specify reasonable obs error statistics.
4. Avoid conflicts of interest.
5. Avoid over-selling results.
6. Only attempt to answer appropriate questions
7. Consider possible effects of any approximations
8. Be critical of your own work
9. Be skeptical of others' works
10. Expose poor work.